

APPLICATIONS OF SIMULATION METHODS TO BARRIER OPTIONS DRIVEN BY LÉVY PROCESSES

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ABSTRACT. In this paper, we apply a mixed Monte Carlo and Quasi-Monte Carlo method, which we proposed in a previous paper, to problems from mathematical finance. We estimate by simulation the Up-and-Out barrier options and Double Knock-Out barrier options. We assume that the stock price of the underlying asset $S = S(t)$ is driven by a Lévy process $L(t)$. We compare our estimates with the estimates obtained by using the Monte Carlo and Quasi-Monte Carlo methods. Numerical results show that an important improvement can be achieved by using the mixed method.

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1. INTRODUCTION

The valuation of financial derivatives is one of the most important problems from mathematical finance. The risk-neutral price of such a derivative can be expressed in terms of a risk-neutral expectation of a random payoff. In some cases, the expectation is explicitly computable, such as the Black & Scholes formula for pricing call and put options on assets modeled by a geometric Brownian motion. However, if we consider call or put options written on assets with non-normal returns, there exists no longer closed form expressions for the price, and therefore numerical methods are involved. Among these methods, Monte Carlo (MC) and Quasi-Monte Carlo (QMC) methods play an increasingly important role.

One of the first applications of the MC method in this field appeared in Boyle [2], who used simulation to estimate the value of a standard European option. Applications of the QMC method to option pricing problems can be found in [13], [16] and [21].

Barndorff-Nielsen [1] proposed to model the log returns of asset prices by using the normal inverse Gaussian (NIG) distribution. This family of non-normal distributions has proven to fit the semi-heavily tails observed in financial time series of various kinds extremely well (see Rydberg [22] or Eberlein and Keller [7]). The time dynamics of the asset prices are modeled by an exponential Lévy process. To price such derivatives, even simple call and put options, we need to consider the numerical evaluation of the expectation. Raible [18] has considered a Fourier method to evaluate call and put options. Alternatives to this method are the MC method or the QMC method. The QMC method has been applied with success in financial applications by many authors (see [8]), and has strong convergence properties. Majority of the work done on applying these simulation techniques to financial problems was in direction where one needs to simulate from the normal distribution. One exception is Kainhofer (see [14]), who proposes a QMC algorithm for NIG variables, based on a technique proposed by Hlawka and Mück (see [12]) to generate low-discrepancy sequences for general distributions.

Barrier options are one of the most important derivatives in the financial markets. In the case of barrier options the general idea is that the payoff depends on whether the underlying asset price hits a predetermined barrier level (see [15]). In this paper we evaluate by simulation the Up-and-Out barrier options and Double Knock-Out barrier options, in the situation where the stock price is modeled by an exponential Lévy process. For the Knock-Out barrier option, the option is valid only as long as the barrier is never touched during the life of the option. For the double Knock-Out barrier options the option is valid only as long as the underlying asset remains above the lower barrier and below the upper barrier until maturity. If the asset price touches either the upper or the lower barrier, then the option is knocked out worthless (zero payoff). Because of the difficulty in obtaining general analytical solutions for barrier options driven by Lévy processes much of the work has been focused on numerical or Monte Carlo valuation methods.

In this paper, we apply the Monte Carlo method, the Quasi-Monte Carlo and a mixed Monte Carlo and Quasi-Monte Carlo method, which we proposed in a previous paper [19], to estimate the value of two types of barrier options.

2. A MIXED MONTE CARLO AND QUASI-MONTE CARLO METHOD

Let us consider the problem of estimating integrals of the form

$$I = \int_{[0,1]^s} f(x)dH(x), \quad (1)$$

where $f : [0,1]^s \rightarrow \mathbb{R}$ is the function we want to integrate and $H : \mathbb{R}^s \rightarrow [0,1]$ is a distribution function on $[0,1]^s$. In the continuous case, the integral I can be rewritten as

$$I = \int_{[0,1]^s} f(x)h(x)dx,$$

where h is the density function corresponding to the distribution function H .

In the MC method (see [23]), the integral I is estimated by sums of the form

$$\hat{I}_N = \frac{1}{N} \sum_{k=1}^N f(x_k),$$

where $x_k = (x_k^{(1)}, \dots, x_k^{(s)})$, $k \geq 1$, are independent identically distributed random points on $[0, 1]^s$, with the common density function h .

In the QMC method (see [23]), the integral I is approximated by sums of the form $\frac{1}{N} \sum_{k=1}^N f(x_k)$, where $(x_k)_{k \geq 1}$ is a H -distributed low-discrepancy sequence on $[0, 1]^s$.

Next, the notions of discrepancy and marginal distributions are introduced.

Definition 2.1 [*H-discrepancy*] Consider an s -dimensional continuous distribution on $[0, 1]^s$, with distribution function H . Let λ_H be the probability measure induced by H . Let $P = (x_1, \dots, x_N)$ be a sequence of points in $[0, 1]^s$. The H -discrepancy of sequence P is defined as

$$D_{N,H}(P) = \sup_{J \subseteq [0,1]^s} \left| \frac{1}{N} A_N(J, P) - \lambda_H(J) \right|,$$

where the supremum is calculated over all subintervals $J = \prod_{i=1}^s [a_i, b_i] \subseteq [0, 1]^s$; $A_N(J, P)$ counts the number of elements of the set (x_1, \dots, x_N) , falling into the interval J , i.e.

$$A_N(J, P) = \sum_{k=1}^N 1_J(x_k).$$

1_J is the characteristic function of J .

The sequence P is called H -distributed if $D_{N,H}(P) \rightarrow 0$ as $N \rightarrow \infty$.

The H -distributed sequence P is said to be a low-discrepancy sequence if $D_{N,H}(P) = \mathcal{O}((\log N)^s/N)$.

The non-uniform Koksma-Hlawka inequality ([3]) gives an upper bound for the approximation error in QMC integration, when H -distributed low-discrepancy sequences are used.

Theorem 2.2 [*non-uniform Koksma-Hlawka inequality*] Let $f : [0, 1]^s \rightarrow \mathbb{R}$ be a function of bounded variation in the sense of Hardy and Krause and (x_1, \dots, x_N)

be a sequence of points in $[0, 1]^s$. Consider an s -dimensional continuous distribution on $[0, 1]^s$, with distribution function H . Then, for any $N > 0$

$$\left| \int_{[0,1]^s} f(x)dH(x) - \frac{1}{N} \sum_{k=1}^N f(x_k) \right| \leq V_{HK}(f)D_{N,H}(x_1, \dots, x_N), \quad (2)$$

where $V_{HK}(f)$ is the variation of f in the sense of Hardy and Krause.

Definition 2.3 Consider an s -dimensional continuous distribution on $[0, 1]^s$, with density function h and distribution function H . For a point $u = (u^{(1)}, \dots, u^{(s)}) \in [0, 1]^s$, the marginal density functions h_l , $l = 1, \dots, s$, are defined by

$$h_l(u^{(l)}) = \underbrace{\int \dots \int}_{[0,1]^{s-1}} h(t^{(1)}, \dots, t^{(l-1)}, u^{(l)}, t^{(l+1)}, \dots, t^{(s)}) dt^{(1)} \dots dt^{(l-1)} dt^{(l+1)} \dots dt^{(s)},$$

and the marginal distribution functions H_l , $l = 1, \dots, s$, are defined by

$$H_l(u^{(l)}) = \int_0^{u^{(l)}} h_l(t) dt.$$

We consider s -dimensional continuous distributions on $[0, 1]^s$, with independent marginals, i.e.,

$$H(u) = \prod_{l=1}^s H_l(u^{(l)}), \quad \forall u = (u^{(1)}, \dots, u^{(s)}) \in [0, 1]^s.$$

This can be expressed, using the marginal density functions, as follows:

$$h(u) = \prod_{l=1}^s h_l(u^{(l)}), \quad \forall u = (u^{(1)}, \dots, u^{(s)}) \in [0, 1]^s.$$

Consider an integer $0 < d < s$. Using the marginal density functions, we construct the following density functions on $[0, 1]^d$ and $[0, 1]^{s-d}$, respectively:

$$h_q(u) = \prod_{l=1}^d h_l(u^{(l)}), \quad \forall u = (u^{(1)}, \dots, u^{(d)}) \in [0, 1]^d,$$

and

$$h_X(u) = \prod_{l=d+1}^s h_l(u^{(l)}), \quad \forall u = (u^{(d+1)}, \dots, u^{(s)}) \in [0, 1]^{s-d}.$$

The corresponding distribution functions are

$$H_q(u) = \int_0^{u^{(1)}} \dots \int_0^{u^{(d)}} h_q(t^{(1)}, \dots, t^{(d)}) dt^{(1)} \dots dt^{(d)},$$

$$u = (u^{(1)}, \dots, u^{(d)}) \in [0, 1]^d, \quad (3)$$

and

$$H_X(u) = \int_0^{u^{(d+1)}} \dots \int_0^{u^{(s)}} h_X(t^{(d+1)}, \dots, t^{(s)}) dt^{(d+1)} \dots dt^{(s)},$$

$$u = (u^{(d+1)}, \dots, u^{(s)}) \in [0, 1]^{s-d}. \quad (4)$$

Next, we present the notion of H -mixed sequence.

Definition 2.4 [*H-mixed sequence*] ([19]) Consider an s -dimensional continuous distribution on $[0, 1]^s$, with distribution function H and independent marginals H_l , $l = 1, \dots, s$. Let H_q and H_X be the distribution functions defined in (3) and (4), respectively.

Let $(q_k)_{k \geq 1}$ be a H_q -distributed low-discrepancy sequence on $[0, 1]^d$, with $q_k = (q_k^{(1)}, \dots, q_k^{(d)})$, and X_k , $k \geq 1$, be independent and identically distributed random vectors on $[0, 1]^{s-d}$, with distribution function H_X , where

$$X_k = (X_k^{(d+1)}, \dots, X_k^{(s)}).$$

A sequence $(m_k)_{k \geq 1}$, with the general term given by

$$m_k = (q_k, X_k), \quad k \geq 1, \quad (5)$$

is called a H -mixed sequence on $[0, 1]^s$.

Let $(m_k)_{k \geq 1}$ be a H -mixed sequence on $[0, 1]^s$, with the general term given by (5).

In order to estimate general integrals of the form (1), we introduce the following estimator.

Definition 2.5 ([19]) Let $(m_k)_{k \geq 1} = (q_k, X_k)_{k \geq 1}$ be an s -dimensional H -mixed sequence, introduced by us in Definition 2.4, with $q_k = (q_k^{(1)}, \dots, q_k^{(d)})$ and $X_k = (X_k^{(d+1)}, \dots, X_k^{(s)})$. We define the following estimator for the integral I :

$$\theta_m = \frac{1}{N} \sum_{k=1}^N f(m_k). \quad (6)$$

We call the method of estimating the integral I , based on the estimator θ_m , defined in (6), *the mixed method*. Theoretical results concerning the mixed method can be found in [9] and [19]. Another combined MC and QMC method is proposed in [20].

3. EVALUATION OF BARRIER OPTIONS BY SIMULATION

In the following, we apply the Monte Carlo method, the Quasi-Monte Carlo method and the mixed method to a problem from mathematical finance, namely the valuation of barrier options. We focus on Up-and-Out barrier options and Double Knock-Out barrier options. The general setting of the problem and the modeling part is presented next.

We consider the situation where the stock price of the underlying asset $S = S(t)$ is driven by a Lévy process $L(t)$,

$$S(t) = S(0)e^{L(t)}. \quad (7)$$

Lévy processes can be characterized by the distribution of the random variable $L(1)$. This distribution can be hyperbolic (see [7]), normal inverse gaussian (NIG), variance-gamma or Meixner distribution.

According to the fundamental theory of asset pricing (see [5]), the risk-neutral price of a barrier option, $C(0)$, is given by

$$C(0) = E^Q(C(\tau, S_\tau)), \quad (8)$$

where $C(\tau, S_\tau)$ is the discounted payoff of the derivative, τ is the first hitting time of the considered barrier price by the underlying asset $S(t)$ and Q is an equivalent martingale measure or a risk-neutral measure. In this paper, we are mostly concerned with exponential NIG-Lévy processes, meaning that $L(t)$ has independent increments, distributed according to a NIG distribution. For a detailed discussion of the NIG distribution and the corresponding Lévy process, we refer to Barndorff-Nielsen [1] and Rydberg [22]. In the situation of exponential NIG-Lévy models, we have an incomplete market, leading to a continuum of equivalent martingale measures Q , which can be used for risk-neutral pricing. Here, we choose the approach of Raible [18] and consider the measure obtained by Esscher transform method. This approach is so-called structure preserving, in the sense that the distribution of $L(1)$ remains in the class of NIG distributions.

In the following, we consider the evaluation of Up-and-Out barrier call options, which have to be valued by simulation. The random variable τ is defined as

$$\tau = \inf\{v \geq 0 | S(v) \geq L\}, \quad (9)$$

where L is the barrier price. The discounted payoff of such an option is

$$C(\tau, S_\tau) = \begin{cases} e^{-rT}(S(T) - K)_+ & , S(t) < L, \forall t \leq T, \text{ i.e. } \tau = T, \\ e^{-r\tau}R & , \tau < T, \end{cases} \quad (10)$$

where the constant K is the strike price, T is the expiration time, R is a prescribed cash rebate and $r > 0$ is a constant risk-free annual interest rate.

Let us assume that the cash rebate is zero, i.e. $R = 0$. Hence, the second part of the discounted payoff is zero. For the risk neutral price $C(0)$ we obtain

$$\begin{aligned} C(0) &= e^{-rT} E^Q((S(T) - K)_+ \cdot I_{\{\sup_{0 \leq t \leq T} S(t) < L\}}) \\ &= e^{-rT} E^Q(\max\{S(T) - K, 0\} \cdot I_{\{\sup_{0 \leq t \leq T} S(t) < L\}}), \end{aligned}$$

where I is the indicator function. If we replace the stock price by (7), we obtain

$$C(0) = e^{-rT} E^Q(\max\{S(0)e^{L(T)} - K, 0\} \cdot I_{\{S(0) \cdot \sup_{0 \leq t \leq T} e^{L(t)} < L\}}). \quad (11)$$

The evaluation of the stock price $S(t)$ should be made at discrete times $0 = t_0 < t_1 < t_2 < \dots < t_s = T$. For simplicity, we focus on regular time intervals, $\Delta t = t_i - t_{i-1}$. We note that

$$X_i = L(t_i) - L(t_{i-1}) = L(t_{i-1} + \Delta t) - L(t_{i-1}) \sim L(\Delta t), \quad i = 1, \dots, s,$$

are independent and identically distributed NIG random variables with the same distribution as $L(t_1)$.

Dropping the discounted factor from the risk-neutral option price, we get the expected payoff under the Esscher transform measure of the Up-and-Out barrier call option

$$\begin{aligned} &E^Q(\max\{S(0)e^{L(T)} - K, 0\} \cdot I_{\{S(0) \cdot e^{\sup_{0 \leq t \leq T} L(t)} < L\}}) = \\ &= E((S(0)e^{\sum_{i=1}^s X_i} - K)_+ \cdot I_{\{S(0) \cdot e^{\max_{1 \leq k \leq s} \{0, \sum_{i=1}^k X_i\}} < L\}}). \end{aligned} \quad (12)$$

Our purpose is to evaluate the expected payoff (12). For this, we rewrite the expectation (12) as a multidimensional integral on \mathbb{R}^s

$$I = \int_{\mathbb{R}^s} \underbrace{\left(S(0)e^{\sum_{i=1}^s x^{(i)}} - K \right)_+ \cdot I_{\{S(0) \cdot e^{\max_{1 \leq k \leq s} \{0, \sum_{i=1}^k x^{(i)}\}} < L\}}}_{E(x)} dG(x) = \int_{\mathbb{R}^s} E(x) dG(x), \quad (13)$$

where $G(x) = \prod_{i=1}^s G_i(x^{(i)})$, $\forall x = (x^{(1)}, \dots, x^{(s)}) \in \mathbb{R}^s$, and $G_i(x^{(i)})$ denotes the distribution function of the so-called log returns induced by $L(t_1)$, with the corresponding density function $g_i(x^{(i)})$. These log increments are independent and NIG distributed, with probability density function

$$f_{NIG}(x; \mu, \beta, \alpha, \delta) = \frac{\alpha}{\pi} \exp(\delta \sqrt{\alpha^2 - \beta^2} + \beta(x - \mu)) \frac{\delta K_1(\alpha \sqrt{\delta^2 + (x - \mu)^2})}{\sqrt{\delta^2 + (x - \mu)^2}} \quad (14)$$

where $K_1(x)$ denotes the modified Bessel function of third type of order 1 (see [17]).

In order to approximate the integral (13), we have to transform it to an integral on $[0, 1]^s$. We can do this using an integral transformation, as follows.

We first consider the family of independent double-exponential distributions with the same parameter $\lambda > 0$, having the cumulative distribution functions $G_{\lambda,i} : \mathbb{R} \rightarrow [0, 1]$, $i = 1, \dots, s$,

$$G_{\lambda,i}(x) = \begin{cases} \frac{1}{2}e^{\lambda x} & , x < 0 \\ 1 - \frac{1}{2}e^{-\lambda x} & , x \geq 0, \end{cases} \quad (15)$$

and the inverses $G_{\lambda,i}^{-1} : [0, 1] \rightarrow \mathbb{R}$, $i = 1, \dots, s$, given by

$$G_{\lambda,i}^{-1}(x) = \begin{cases} \frac{1}{\lambda} \log(2x) & , x \leq \frac{1}{2} \\ -\frac{1}{\lambda} \log(2 - 2x) & , x > \frac{1}{2}. \end{cases} \quad (16)$$

Next, we consider the substitutions $x^{(i)} = G_{\lambda,i}^{-1}(1 - y^{(i)})$, $i = 1, \dots, s$, and then take $y^{(i)} = 1 - z^{(i)}$, $i = 1, \dots, s$.

The integral (13) becomes

$$\begin{aligned} I &= \int_{[0,1]^s} \underbrace{\left(S(0)e^{\sum_{i=1}^s G_{\lambda,i}^{-1}(z^{(i)})} - K \right)_+ \cdot I_{\{S(0) \cdot e^{\max_{1 \leq k \leq s} \{0, \sum_{i=1}^k G_{\lambda,i}^{-1}(z^{(i)})\}} < L\}}}_{f(z)} dH(z) \\ &= \int_{[0,1]^s} f(z) dH(z), \end{aligned} \quad (17)$$

where $H : [0, 1]^s \rightarrow [0, 1]$, defined by

$$H(z) = \prod_{i=1}^s (G_i \circ G_{\lambda,i}^{-1})(z^{(i)}), \quad \forall z = (z^{(1)}, \dots, z^{(s)}) \in [0, 1]^s, \quad (18)$$

is a distribution function on $[0, 1]^s$, with independent marginals $H_i = G_i \circ G_{\lambda,i}^{-1}$, $i = 1, \dots, s$.

In conclusion, we want to estimate the integral (17). This can be done using the Monte Carlo method, the Quasi-Monte Carlo method, as well the mixed Monte Carlo and Quasi-Monte Carlo method proposed by us.

In the case of a Double Knock-Out barrier call option, reasoning and modeling in a similar way, we need to estimate the following integral:

$$\begin{aligned} I &= \int_{[0,1]^s} \underbrace{f(z) \cdot I_{\{S(0) \cdot e^{\min_{1 \leq k \leq s} \{0, \sum_{i=1}^k G_{\lambda,i}^{-1}(z^{(i)})\}} > L\}}}_{p(z)} dH(z) \\ &= \int_{[0,1]^s} p(z) dH(z), \end{aligned} \quad (19)$$

where l is the lower barrier, L is the upper barrier and $H : [0, 1]^s \rightarrow [0, 1]$, defined by

$$H(z) = \prod_{i=1}^s (G_i \circ G_{\lambda,i}^{-1})(z^{(i)}), \quad \forall z = (z^{(1)}, \dots, z^{(s)}) \in [0, 1]^s, \quad (20)$$

is a distribution function on $[0, 1]^s$, with independent marginals $H_i = G_i \circ G_{\lambda,i}^{-1}$, $i = 1, \dots, s$.

4. NUMERICAL EXPERIMENTS

In the following, we compare numerically our mixed method with the MC and QMC methods. As a measure of comparison, we will use the absolute errors produced by these three methods in the approximation of the integrals (17) and (19).

4.1 THE MC, QMC AND MIXED ESTIMATES

The MC estimate is defined as follows:

$$\theta_{MC} = \frac{1}{N} \sum_{k=1}^N f(x_k^{(1)}, \dots, x_k^{(s)}), \quad (21)$$

where $x_k = (x_k^{(1)}, \dots, x_k^{(s)})$, $k \geq 1$, are independent identically distributed random points on $[0, 1]^s$, with the common distribution function H defined in (20).

In order to generate such a point x_k , we proceed as follows. We first generate a random point $\omega_k = (\omega_k^{(1)}, \dots, \omega_k^{(s)})$, where $\omega_k^{(i)}$ is a point uniformly distributed on $[0, 1]$, for each $i = 1, \dots, s$. Then, for each component $\omega_k^{(i)}$, $i = 1, \dots, s$, we apply the inversion method (see [4] and [6]), and obtain that $H_i^{-1}(\omega_k^{(i)}) = (G_{\lambda,i} \circ G_i^{-1})(\omega_k^{(i)})$ is a point with the distribution function H_i . As the s -dimensional distribution with the distribution function H has independent marginals, it follows that $x_k = ((G_{\lambda,1} \circ G_1^{-1})(\omega_k^{(1)}), \dots, (G_{\lambda,s} \circ G_s^{-1})(\omega_k^{(s)}))$ is a point on $[0, 1]^s$, with the distribution function H . As we can see, in order to generate non-uniform random points on $[0, 1]^s$, with distribution function H , we need to know the inverse of the distribution function of a NIG distributed random variable or, at least an approximation of it. As the inverse function is not explicitly known, an approximation of it is needed in our simulations. In order to obtain an approximation of the inverse, we use the Matlab function "niginv" as implemented by R. Werner, based on a method proposed by K. Prause in his Ph.D. dissertation [17].

The QMC estimate is defined as follows:

$$\theta_{QMC} = \frac{1}{N} \sum_{k=1}^N f(x_k^{(1)}, \dots, x_k^{(s)}), \quad (22)$$

where $x = (x_k)_{k \geq 1}$ is a H -distributed low-discrepancy sequence on $[0, 1]^s$, with $x_k = (x_k^{(1)}, \dots, x_k^{(s)})$, $k \geq 1$.

In order to generate such a sequence, we apply a method proposed by Hlawka and Mück in [12]. In their method, they create directly H -distributed low-discrepancy sequences, where H can be any distribution function on $[0, 1]^s$, with density function h , which can be factored into a product of independent, one-dimensional densities. The method is based on the following theoretical result.

Theorem 4.1 ([11]) *Consider an s -dimensional continuous distribution on $[0, 1]^s$, with distribution function H and density function $h(u) = \prod_{j=1}^s h_j(u^{(j)})$, $\forall u = (u^{(1)}, \dots, u^{(s)}) \in [0, 1]^s$. Assume that $h_j(t) \neq 0$, for almost every $t \in [0, 1]$ and for all $j = 1, \dots, s$. Furthermore, assume that h_j , $j = 1, \dots, s$, are continuous on $[0, 1]$. Denote by $M_f = \sup_{u \in [0, 1]^s} f(u)$. Let $\omega = (\omega_1, \dots, \omega_N)$ be a sequence in $[0, 1]^s$. Generate the sequence $x = (x_1, \dots, x_N)$, with*

$$x_k^{(j)} = \frac{1}{N} \sum_{r=1}^N [1 + \omega_k^{(j)} - H_j(\omega_r^{(j)})] = \frac{1}{N} \sum_{r=1}^N 1_{[0, \omega_k^{(j)}]}(H_j(\omega_r^{(j)})), \quad (23)$$

for all $k = 1, \dots, N$ and all $j = 1, \dots, s$, where $[a]$ denotes the integer part of a . Then the generated sequence x has a H -discrepancy of

$$D_{N,H}(x_1, \dots, x_N) \leq (2 + 6sM_f)D_N(\omega_1, \dots, \omega_N).$$

As our distribution function H can be factored into independent marginals, and has the support on $[0, 1]^s$, we can apply directly the above theorem, to generate H -distributed low-discrepancy sequences. During our experiments, we employed as low-discrepancy sequences $\omega = (\omega_k)_{k \geq 1}$ on $[0, 1]^s$, the Halton sequences (see [10]).

All points constructed by the Hlawka-Mück method are of the form i/N , $i = 0, \dots, N$, in particular some elements of the sequence $x = (x_1, \dots, x_N)$ might assume a value of 0 or 1. A value of 1 is a singularity of the function $f(x)$, due to the logarithm from the definition of $G_{\lambda, i}^{-1}(x)$, which becomes unbounded if $x = 1$. Hence, the sequence constructed with Hlawka-Mück method is not directly suited for unbounded problems. To overcome this problem, Kainhofer (see [14]) suggests to define a new sequence, in which the value 1 is replaced by $1/N$, where N is the number of points in the set. This slight modification of the sequence is shown to have a minor influence, as the transformed set does not lose its low-discrepancy and can be used for QMC integration.

The H -mixed estimate proposed by us earlier is:

$$\theta_m = \frac{1}{N} \sum_{k=1}^N f(q_k^{(1)}, \dots, q_k^{(d)}, X_k^{(d+1)}, \dots, X_k^{(s)}), \quad (24)$$

where $(q_k, X_k)_{k \geq 1}$ is an s -dimensional H -mixed sequence on $[0, 1]^s$.

In order to obtain such a H -mixed sequence, we first construct the H_q -distributed low-discrepancy sequence $(q_k)_{k \geq 1}$ on $[0, 1]^d$, using the Hlawka-Mück method (the distribution function H_q was defined in (3)). Next, we generate the independent and identically distributed random points $x_k, k \geq 1$ on $[0, 1]^{s-d}$, with the common distribution function H_X , using the inversion method (the distribution function H_X was defined in (4)). Finally, we concatenate q_k and x_k for each $k \geq 1$, and get our H -mixed sequence on $[0, 1]^s$.

In our experiments, we used as low-discrepancy sequences on $[0, 1]^d$, for the generation of H -mixed sequences, the Halton sequences (see [10]).

We suppose that the parameters of the NIG-distributed log-returns under the equivalent martingale measure given by the Esscher transform are given by

$$\mu = 0.00079 * 5, \beta = -15.1977, \alpha = 136.29, \delta = 0.0059 * 5, \quad (25)$$

and they are the same as in Kainhofer (see [14]). We observe that these parameters are relevant for daily observed stock price log-returns (see [22]). As the class of NIG distributions is closed under convolution, we can derive weekly stock prices by using a factor of 5 for the parameters μ and δ .

4.2 UP-AND-OUT BARRIER OPTIONS

We suppose that the initial stock price is $S(0) = 100$, the strike price is $K = 100$, the barrier price is $L = 120$ and the risk-free annual interest rate is $r = 3.75\%$. We choose the parameter of the double-exponential distribution $\lambda = 95.2271$.

The barrier option is sampled at weekly time intervals. We also let the option to have maturities of $s = 32$ weeks. Hence, our problem is a 32 multidimensional integral, over the payoff function.

We are going to compare the three estimates in terms of their absolute error, where the "exact" option price is obtained as the average of 10 MC simulations, with $N = 400000$ for the initial integral (13).

In our tests we considered the dimension $s = 32$ of the transformed integral (17) on $[0, 1]^s$. The MC and H -mixed estimates are the mean values of 10 independent runs, while the QMC estimate is the result of a single run. The results are presented in Figure 1, where the number of samples N varies from 5000 to 10000 with a step of 200.

We performed numerical tests for different values of d , the deterministic part of the H -mixed sequence. We noticed that, in order to achieve a good performance of the mixed method, the value of d should be around one third of the dimension of the problem, confirming the conclusions from paper [19], concerning the choice of d .

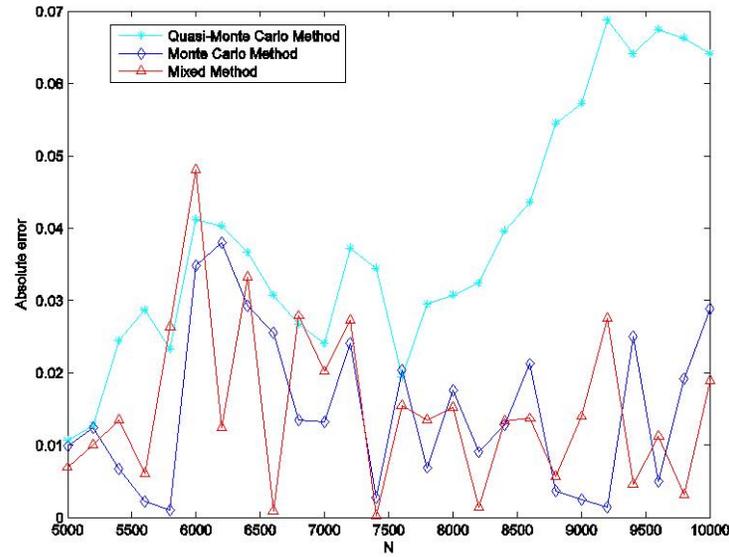


Figure 1: Simulation results for $s = 32$ and $d = 10$ for the Up-and-Out barrier call option.

We can conclude that our mixed method can give considerable improvements over the MC method in almost half of the situations and over the QMC method in almost all of the situations, in estimating Up-and-Out barrier options driven by Lévy processes. Also, the absolute errors for all three estimates are very small, even for small sample sizes.

4.3 DOUBLE KNOCK-OUT BARRIER OPTIONS

We assume that the initial stock price is $S(0) = 110$, the strike price is $K = 100$, the upper barrier price is $L = 120$, the lower barrier price is $l = 90$ and the risk-free annual interest rate is $r = 3.75\%$. We choose the parameter of the double-exponential distribution $\lambda = 95.2271$.

We are going to compare the three estimates in terms of their absolute error, where the "exact" barrier option price is obtained as the average of 10 MC simulations, with $N = 400000$ for the initial integral.

In our tests we considered the dimension $s = 32$ of the transformed integral (19) on $[0, 1]^s$. The MC and H -mixed estimates are the mean values of 10 independent runs, while the QMC estimate is the result of a single run. The numerical results are presented in Figure 2, where the number of samples N varies from 5000 to 10000

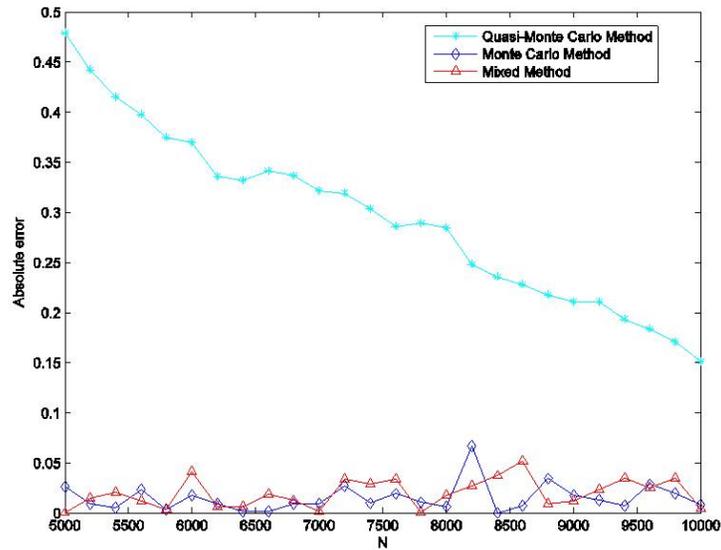


Figure 2: Simulation results for $s = 32$ and $d = 10$ for the Double Knock-Out barrier call option.

with a step of 200.

We performed numerical tests for different values of d . We noticed that, to achieve a good performance of the mixed method, the value of d should be 10, which is around one third of the dimension of the problem and which confirms the conclusions from paper [19] concerning the choice of d .

From the simulation results, we conclude that our mixed method can give considerable improvements over the MC method in almost half of the situations and over the QMC method in all of the situations, in estimating Double Knock-Out barrier options driven by Lévy processes. Also, we notice that the absolute errors for all three estimates are very small, even for small sample sizes.

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